

BU CS599 S1
Foundations of Private Data Analysis
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Lecture 14: DP-FTRL

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Today

- What's wrong with DP-SGD and amplification
- Gradient descent as online sums
- Tree mechanism recall
- DP-FTRL mechanism
- Error analysis

What's wrong with DP-SGD?

- DP-SGD requires either
 - Evaluating the entire gradient at each step (time $\Omega(nd)$), or
 - Amplification by subsampling
 - Requires having all the data in one place, randomly permuting it
 - Data needs to fit in memory ☹
- Today: algorithm with weaker guarantees but similar empirical performance
 - Basic idea: gradient descent is a continually updated sum
$$w_{t+1} = w_t + \eta g_t \quad \text{where } g_t \approx \nabla L(w_t)$$
$$= w_1 + \eta \sum_{i=1}^t g_i$$
 - Idea: At every time step, approximate $s_t := \sum_{i=1}^t g_i$.

Tree Mechanism (Vector Version)

- Receives stream of update vectors
 $g_1, g_2, \dots, g_T \in \mathbb{R}^d$ with $\|g_i\| \leq 1$
(we use $T = n$)
- Outputs $\tilde{s}_t = s_t + Z_t$ where Z_t is tree mechanism noise and $s_t = \sum_{i=1}^t g_i$.
 - Each node $[i, j]$ in binary tree releases its sum plus noise $V_u \sim N(0, \sigma^2 \mathbb{I}_d)$
 - $Z_t = V_{u_1} + \dots + V_{u_k}$ where $k \approx \log_2 T$
- **Accuracy:** For all $\beta > 0$, with probability $\geq 1 - \beta$, the Z_t 's satisfy
$$\frac{1}{T} \sum_{t=1}^T \|Z_t\| \leq \sigma \sqrt{d \log T \ln 1/\beta}$$
- **Privacy:** If
 - g_t depends only on x_t and previous outputs $\tilde{s}_1, \dots, \tilde{s}_{t-1}$,
 - and $\sigma = 2\sqrt{\log T \log 1/\delta} / \varepsilon$,then Tree Mechanism satisfies (ε, δ) -DP (and $(\sigma\sqrt{\log T})$ -GDP).

DP-FTRL for continuous optimization

(with batch size 1 and the tree mech)

$\mathcal{A}(x_1, \dots, x_n)$:

➤ $w_1 = \vec{0}$

➤ For $t = 1$ to $T = n$:

➤ $g_t = \text{clip}(\nabla \ell(w_t; x_t))$

➤ $\tilde{s}_t = (\text{TreeMechanism with update } g_t)$

➤ $w_{t+1} = \arg \min_{w \in C} \left(\langle \tilde{s}_t, w \rangle + \frac{\lambda}{2} \|w\|^2 \right)$
(This is the same as $w_1 - \frac{1}{\lambda} \tilde{s}_t$ when $C = \mathbb{R}^d$)

➤ Return $\bar{w} = \frac{1}{T} \sum_{i=1}^T w_t$

Privacy: TreeMechanism. (Each data point only affects 1 tree entry. Subtle point: inputs are adaptive. Ok because of Gaussian mechanism.)

Analyzing convergence via regret

Theorem: Suppose ℓ is 1-Lipschitz and convex, and $\mathcal{C}$ is convex.

For all $x_1, \dots, x_n$, and all $w^* \in \mathcal{C}$, w.p. $\geq 1 - \beta$:

$$\begin{aligned} R &= \frac{1}{n} \sum_t \ell(w_t; x_t) - \frac{1}{n} \sum_t \ell(w^*, x_t) \\ &= \frac{(\text{Tree mech. error})}{\lambda} + \frac{1}{\lambda} + \frac{\lambda}{2n} \|w^*\|^2 \end{aligned}$$

where $(\text{Tree mech error}) = O\left(\frac{1}{\varepsilon} \sqrt{d \log^2 n \log \frac{1}{\delta} \log \frac{1}{\beta}}\right)$.

This is called an **external regret** bound.

Can choose λ to get $R = \tilde{O}\left(\sqrt{\frac{\sqrt{d}}{\varepsilon n}}\right)$. Why is this useful?

Why is this useful?

- Suppose data drawn i.i.d. from P
- Define $L_P(w) := \mathbb{E}_{X \sim P} \ell(w; X)$
- **Lemma** (“online to batch conversion”):
$$\mathbb{E}_{\substack{X_1, \dots, X_n \sim P \\ \text{coins of } A}} (L_P(\bar{w})) \leq L_P(w^*) + (*).$$
- Proof: Exercise. (Hint: x_t is independent of w_t .)

Proving Main Theorem: Noise Terms

- Consider, for each t , the counterfactual nonprivate iterate

$$w'_t = \arg \min_{w \in C} \left(\sum_i^t g_i + \frac{\lambda}{2} \|w\|^2 \right), \text{ roughly } \frac{s_t}{\lambda}.$$

- $R = \frac{1}{n} \sum_t \ell(w_t; x_t) - \frac{1}{n} \sum_t \ell(w^*; x_t) \leq \frac{1}{n} \sum_t \langle g_t, w_t - w^* \rangle$

➤ Use the linear tangent to $\ell(\cdot; x_t)$ at w_t

- $\frac{1}{n} \sum_t \langle g_t, w_t - w^* \rangle = \underbrace{\frac{1}{n} \sum_t \langle g_t, w_t - w'_t \rangle}_{\text{"noise"}} + \underbrace{\frac{1}{n} \sum_t \langle g_t, w'_t - w^* \rangle}_{\text{"regret"}}$

- Let's bound the noise term when $C = \mathbb{R}$, for simplicity:

$$\begin{aligned} \text{➤ } \frac{1}{n} \sum_t \langle g_t, w_t - w'_t \rangle &= \frac{1}{n} \sum_t \left\langle g_t, \frac{s_t}{\lambda} - \frac{\tilde{s}_t}{\lambda} \right\rangle = -\frac{1}{n} \sum_t \frac{\langle g_t, Z_t \rangle}{\lambda} \\ &\leq \frac{n}{n} \cdot \frac{\|g_t\| \|Z_t\|}{\lambda} \leq \frac{(\text{Tree Mech. error})}{\lambda}. \end{aligned}$$

Proving Main Theorem: Regret

- We need to bound $\frac{1}{n} \sum_t \langle g_t, w'_t - w^* \rangle$
 - Let $r_t := \langle g_t, w'_t - w^* \rangle$, so we are bounding $\frac{1}{n} \sum r_t$
- Again, assume $\mathcal{C} = \mathbb{R}$ for simplicity
- Consider potential function $\Phi_t = \frac{1}{2} \|w'_t - w^*\|^2$.
- **Claim:** $\Phi_t - \Phi_{t+1} \geq \frac{1}{\lambda} r_t - \frac{1}{2\lambda^2} \|g_t\|^2$
 - Proof by expanding Φ_t 's as squares
 - Equivalent statement: $r_t \leq \lambda(\Phi_t - \Phi_{t+1}) + \frac{1}{2\lambda} \|g_t\|^2$.
- Thus
$$\frac{1}{n} \sum r_t \leq \frac{\lambda}{n} \left(\sum_t (\Phi_t - \Phi_{t+1}) + \frac{1}{2\lambda^2} \sum_t \|g_t\|^2 \right)$$
$$\leq \frac{\lambda \Phi_1}{n} + \frac{1}{2\lambda} = \frac{\lambda \|w^*\|}{n} + \frac{1}{2\lambda}.$$

QED ☺

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Takeaway: DP-FTRL provides

- an alternative to DP-SGD with similar computational performance
- without requiring randomly ordered / sampled data for privacy.

Consequently, it is much easier to implement at scale.