## Privacy in Statistics and Machine LearningSpring 2021In-class Exercises for Lecture 15 (Multiplicative Weights)March 23, 2021

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Problems with marked with an asterisk (\*) are more challenging or open-ended.

- (Online Learning Requires Randomization) Show that for every method D that plays deterministic actions (where p<sup>t</sup> puts probability 1 on a single action) there is an adversary for which D's average regret is Ω(1).
- 2.  $(\sqrt{\ln(k)/T} \text{ lower bound})$  Show that for any method (randomized or not), if the adversary picks cost vectors unformly at random in  $\{0, 1\}^k$ , the expected regret will be  $\Theta(\sqrt{\log(k)/T})$ . (*Hint:* The expected cost paid by the algorithm is exactly T/2. Show that in hindsight, with probability at least 1/2, one of the choices will have cost less than  $\frac{T}{2} \Omega(\sqrt{T \ln(k)})$ .)

This means that the guarantee obtained by multiplicative weights is tight, in general.

- 3. (MW with a perfect action) Suppose we know ahead of time that there is a perfect choice a\* that always has cost 0. Show that we can set η so that the algorithm achieves total cost at most 2 ln(k). (Be careful: our proof required η to be at most 1/2.)
- 4. (\*) Show that if we know *OPT* ahead of time, we can set  $\eta$  to get an average cost of at most  $\frac{OPT}{T} + \frac{2}{T}\sqrt{\ln(k) \cdot \max(OPT, \ln(k))}$ .
- 5. Theorem 3.1 requires us to know the number of steps *T* ahead of time. Show that one can modify the algorithm to adapt automatically to the length of the process. Specifically, there is a standard trick known as "repeated doubling": we start the algorithm assuming we will run for  $T_0 = 4 \ln(k)$  steps. If the number of steps exceeds  $T_0$ , we restart the algorithm assuming a length of  $T_1 = 2T_0$ . If the number of steps exceeds  $T_0 + T_1$ , we expand our time horizon to  $T_2 = 2T_1$ , and so on. Show that this variation achieves average regret  $O(\sqrt{\ln(k)/T})$  of *T* (without knowing *T*).
- 6. How important is the fact that probabilities of higher-cost actions be selected with exponentially small probability? Consider an algorithm that, at each time *t*, selects action *a* with probability that scales polynomially in its cost so far  $c_a^{<t}$ . Specifically, suppose  $p_a^t \propto \frac{1}{1+c_a^{<t}}$ . Show a sequence of cost vectors on which the algorithm has expected average regret at least  $\Omega(k/T)$  (one can prove a stronger bound; but even this bound hightlights the bad dependency on *k*).